



CHES & LEPP

Video-based X-Ray Beam Position Monitoring at CHES

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Basic Types of XBPMs:

Intercepting

Most fluorescent
screens

barely intercepting

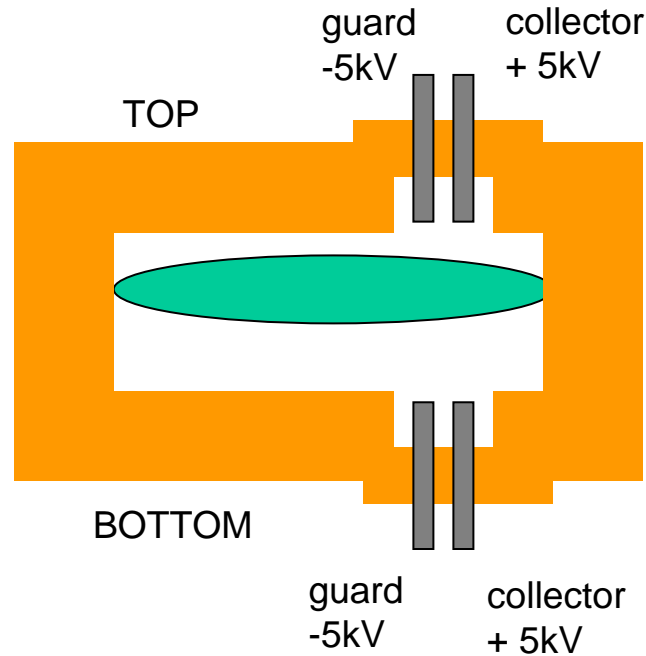
photo-electron types
wires
lateral photo-diodes

non-intercepting

Gas luminescence



Photo-Electron Beam Position Monitor for CHESW wiggler beam lines



EPP

Disadvantage:

Measures the fringes only:
Hard bend contamination.

Benefits:

Fast, robust, reliable

Possible problems:

Linearity?

$$T = \alpha I_0 x + \beta,$$
$$B = \alpha' I_0 (1-x) + \beta'$$

For symmetrical and linear detector:

$$x \sim D/S = (T-B)/(T+B)$$



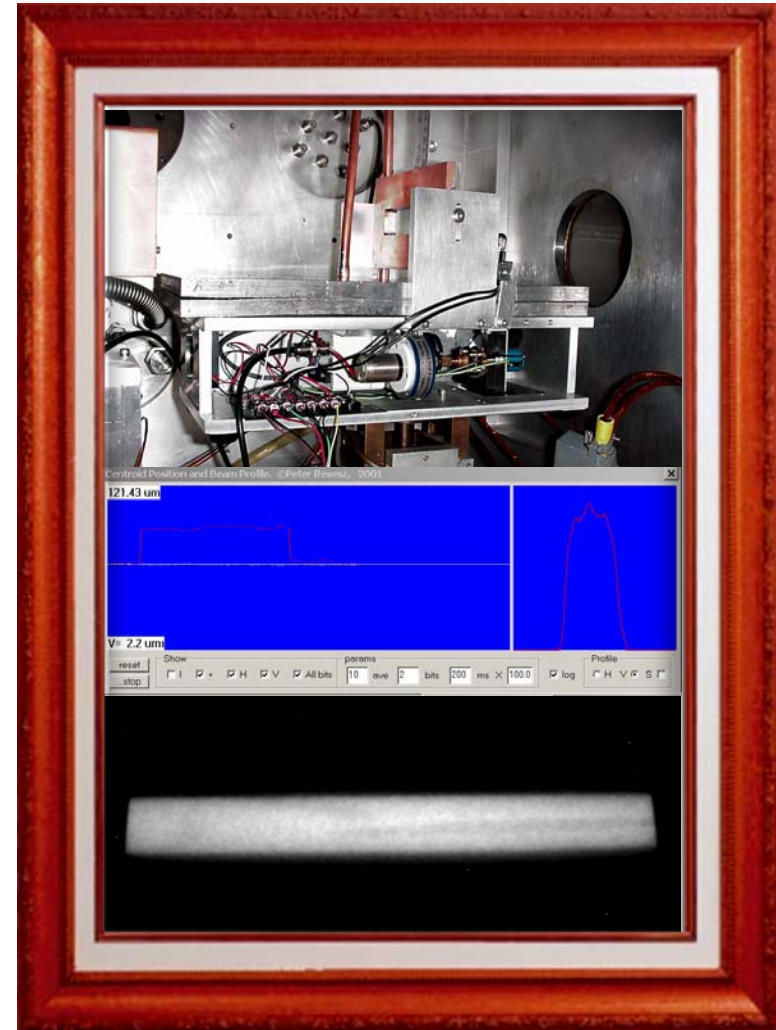
The Classics form 2002 VBPM exhibition at G-line



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He gas luminescence



Diamond screen



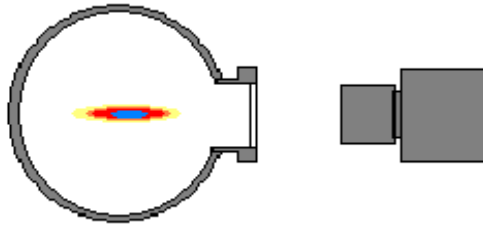
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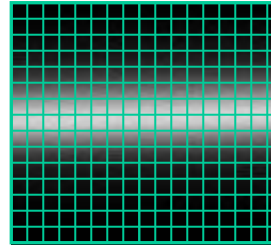
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The Principle of VBPM

Camera setup



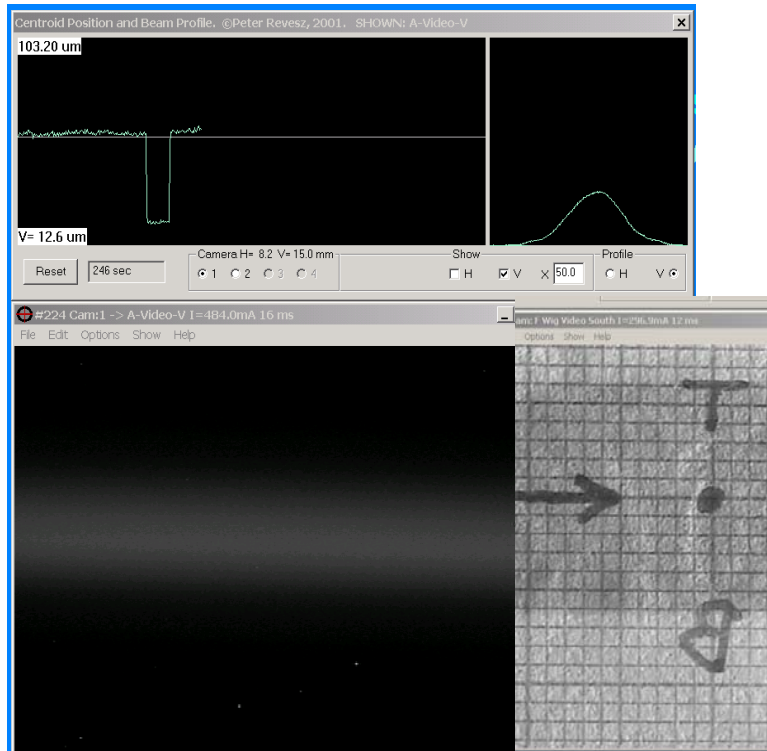
Captured image



Centroid position

$$X_c := \frac{\sum_{(i,j)} i \cdot G(i,j)}{\sum_{(i,j)} G(i,j)}$$

$$Y_c := \frac{\sum_{(i,j)} j \cdot G(i,j)}{\sum_{(i,j)} G(i,j)}$$



X_c and Y_c in pixels, but
It is easy to cross-calibrate to
microns by imaging a mm-grid.

No Z-jack is needed, the whole system
can be mounted rigidly.

It is not just a “number” but visual
information as well. Important also
as a diagnostic tool.





Advantages and Disadvantages of VBPMs

PRO

- Non-intercepting
- Visual information
- Position is basically what the user has
- Provides beam profile
- No Z-jack needed, easy calibration
- Beam size information
- Beam intensity information

CON

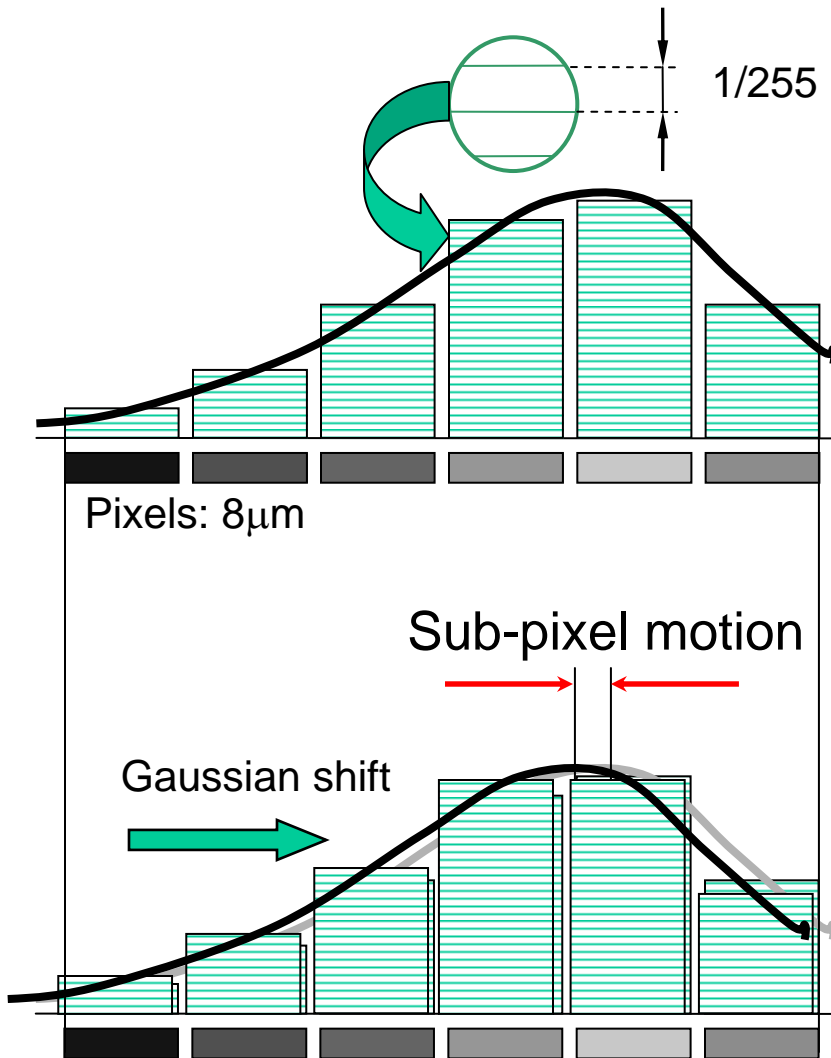
- More complicated H/W
- Requires special software
- Requires computer
- For analog cameras: noise creates artifact beam motion
- Non-vacuum
- Possible radiation degradation
- “Zingers”



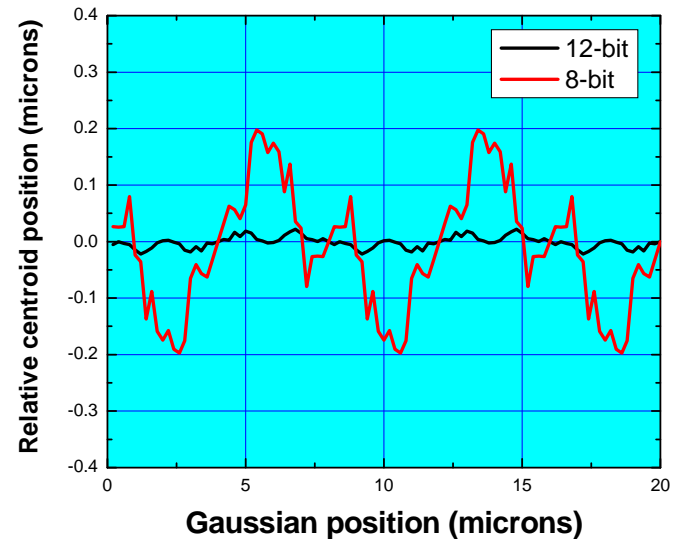


How sensitive is the centroid measurement?

8-bit digitalization: 255 Grayscale steps



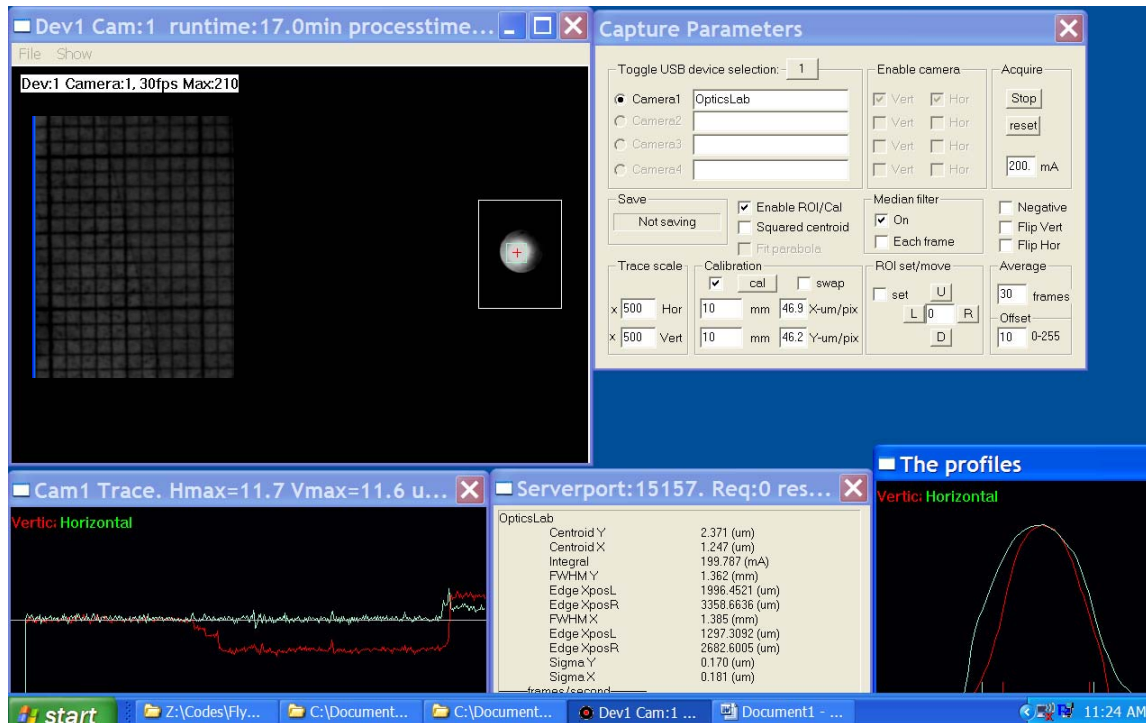
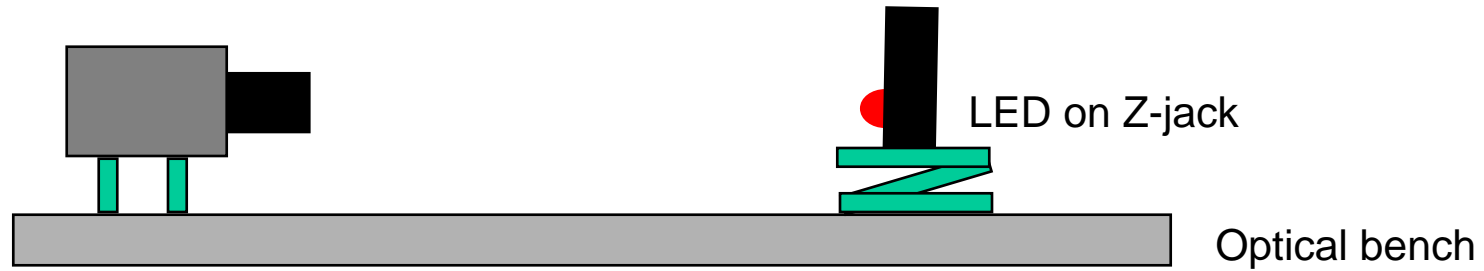
Computer simulation





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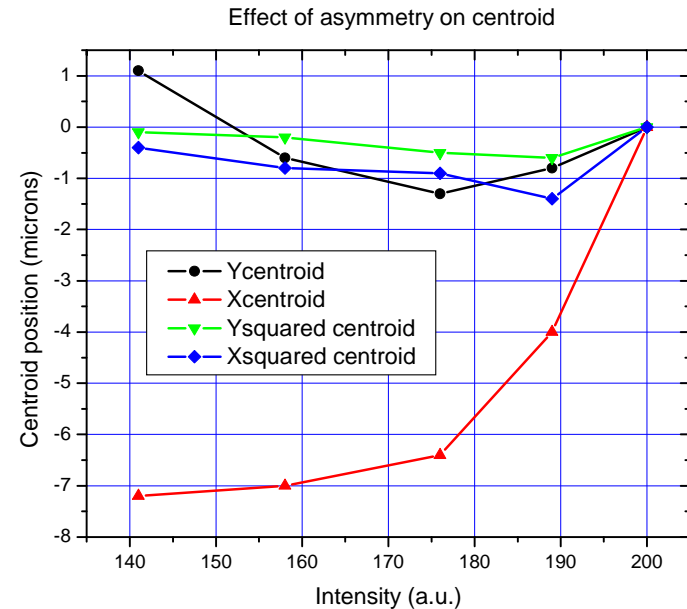
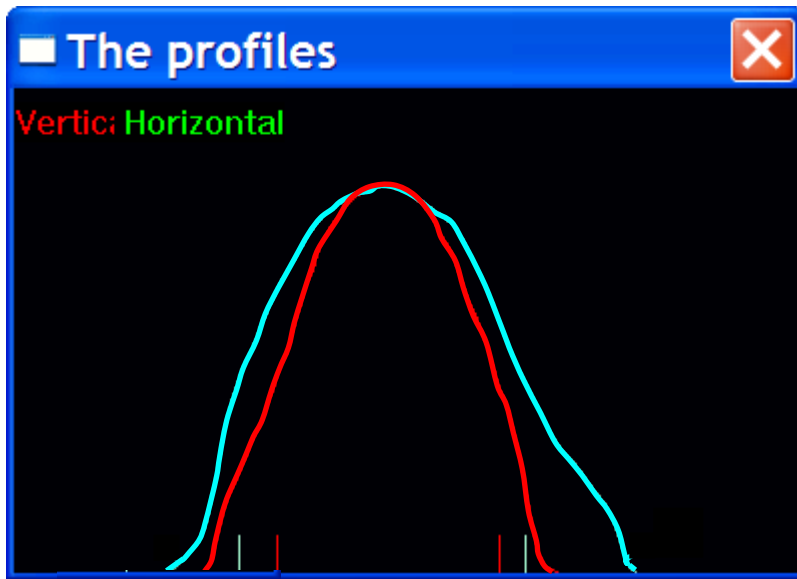
Bench test of centroid position sensitivity



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Linearity and Offset



The use of squared centroid helps to reduce the artifact due to offset an asymmetry

$$\text{Squared centroid : } x_{sqc} = \frac{\sum x \cdot I^2(x, y)}{\sum I^2(x, y)}$$

-Helps to reduce the effect of offset for asymmetric profiles.





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VBPM program and architecture

Beam lines

Analog cameras, Sensoray 4 input USB 2.0 frame capture devices



Camera/Image control

For multiple cameras:

- Enable/Disable cameras
- Set ROIs
- Adjustments:
 - Brightness, gain, offset, averaging
- Calculate:
 - centroids, Intensity, FWHMs, edges

Display:

Image, centroids, trace, profiles

Calibrate:

Pixel-to-micron
Intensity-to-mA

Frame Capture:

- Get pixel data in ROI
- Adjustments:
 - median, rotation, flip
- Calculate:
 - centroids, Intensity, FWHMs, edges, standard deviations

Display:

Image, centroids, trace, profiles

Communicate:

- Accept UDP connection from server
- Accept and respond to:
 - SENDALL
 - LISTALL and SENDBYNAME
- Send data





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VBPM Centroid program user interface

The screenshot displays the VBPM Centroid program interface with several windows:

- Dev2 Cam:3**: Main window showing camera settings and a live image of a beam profile.
- Capture Parameters**: Panel for configuring camera selection (Camera1-FW_PM_V, Camera2-XX_PM_V, Camera3-FH_PM_V, Camera4-G2_PM_V), enabling cameras, and setting acquisition parameters like current (200 mA).
- The profiles**: Window showing a red beam profile on a black background, labeled "Vertical".
- Serverport:15153**: Window displaying a list of camera parameters and their values for FW_PM_V and FH_PM_V.
- Cam3 Trace**: Window showing a trace plot with parameters Hmax=0.0, Vmax=146.2 um, span=35.0min.
- Reset parameters**: Panel for adjusting ROI rotation and display options.
- Settings dev2 cam3**: Panel for adjusting brightness and contrast.

Allows to control 12 cameras,

Allows operator to visually inspect all camera images to optimize settings,

Transmits positions, width, intensity to signal collector program,

Saves data,
Saves/retrieves system configuration



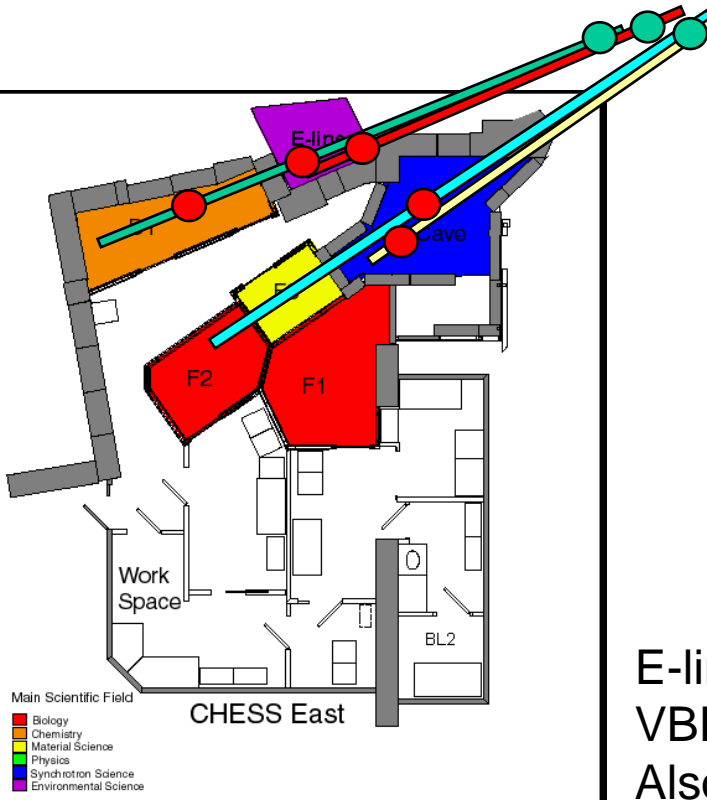
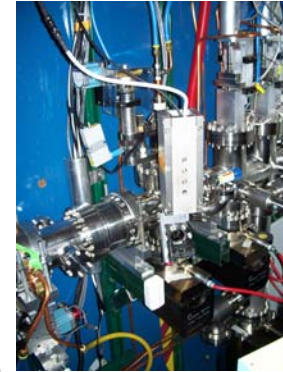


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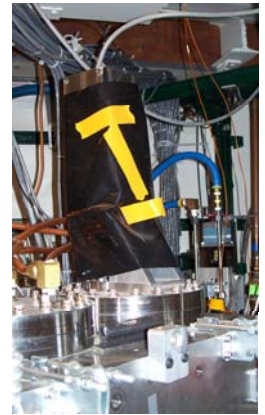
CHES-East Position monitors

- VBPM
- P.E

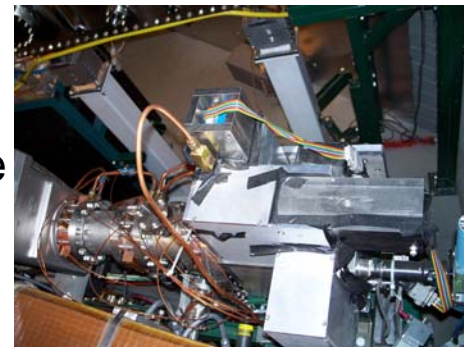
D-line diamond VBPMs in tunnel
And cave



F1-F3-line
He VBPMs
in cave



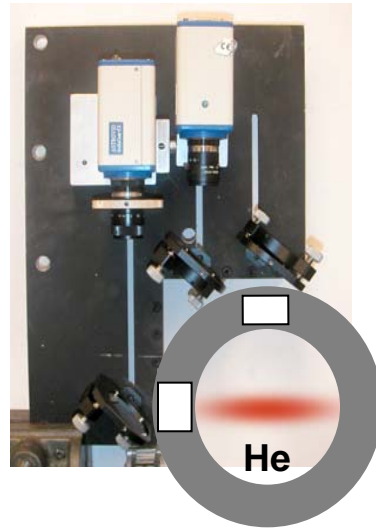
E-line He
VBPM in tunnel
Also source size
measurement



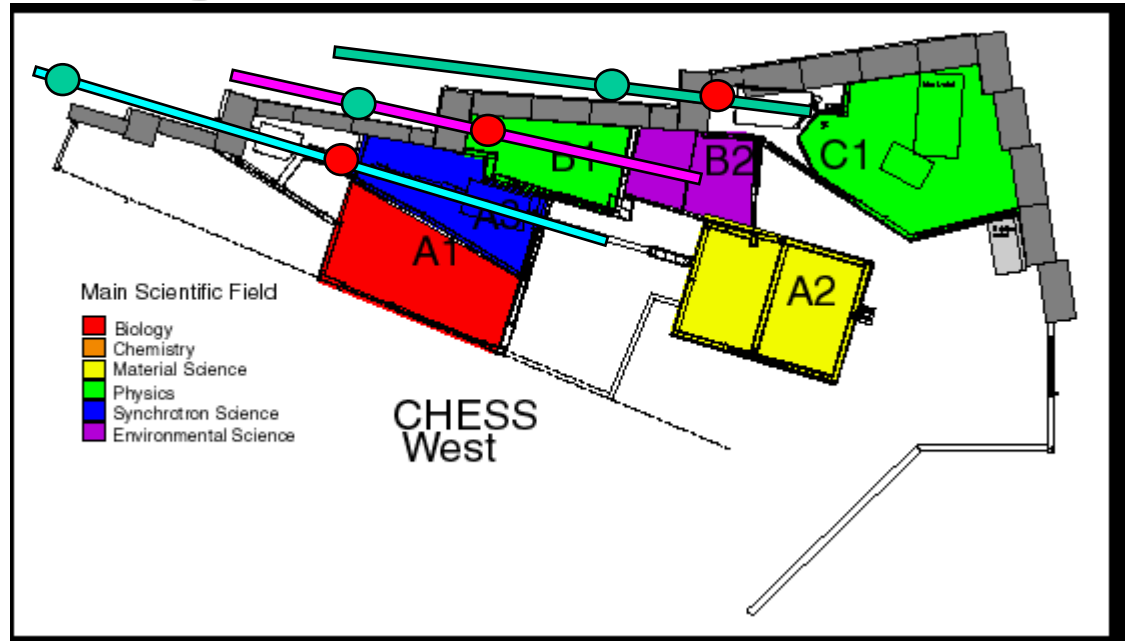


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CHES-West Position monitors



- VBPM
- P.E

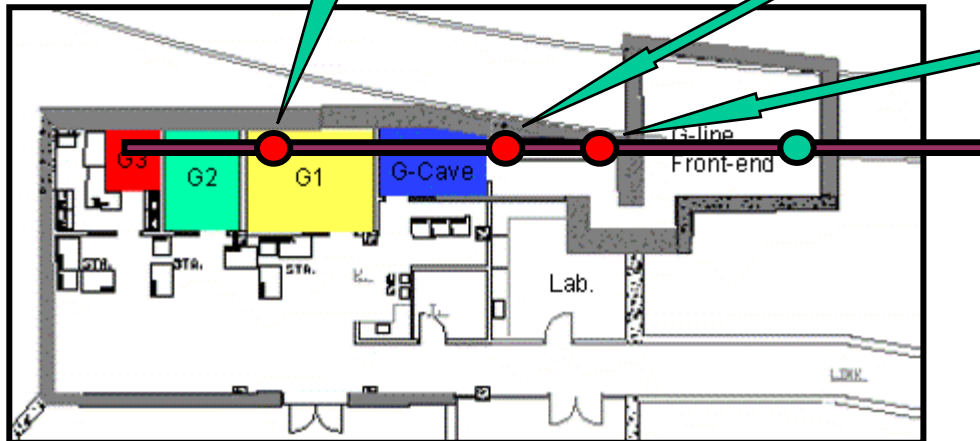
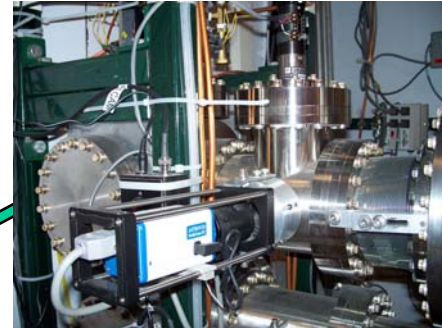




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CHES-G-line Position monitors

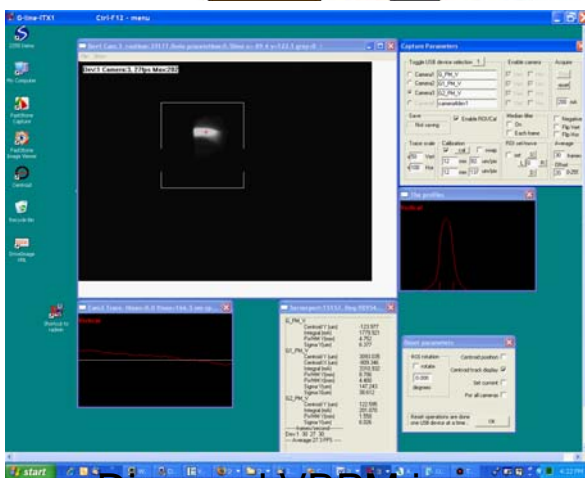
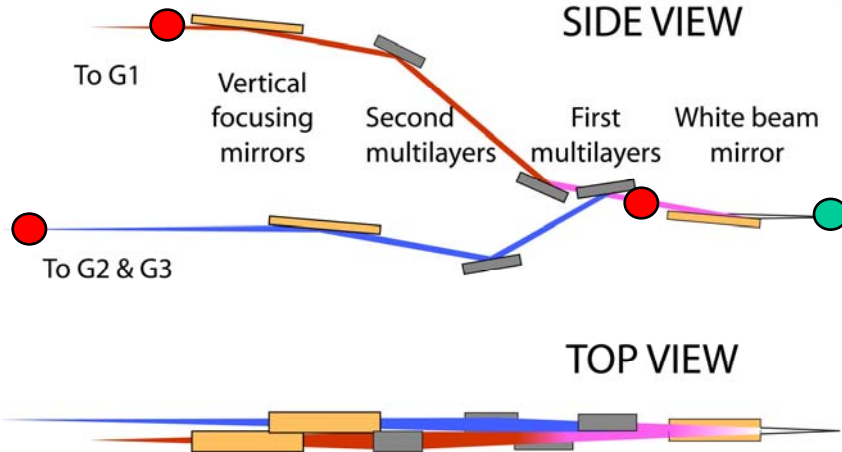
- VBPM
- P.E



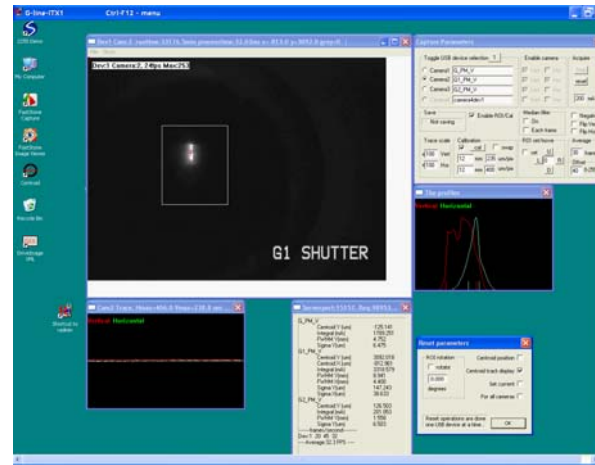
CHES-G-line Position monitors



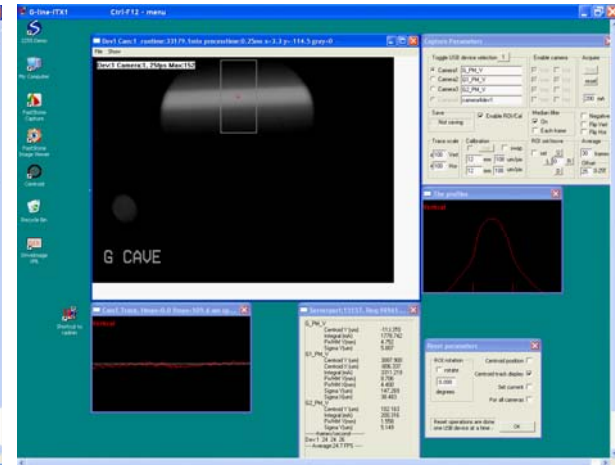
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Diamond VBPM image at G2 beam passed multilayers and focusing mirrors



Diamond Video BPM image at G1 shutter location (passed multilayers and focusing). Spill-over is seen.

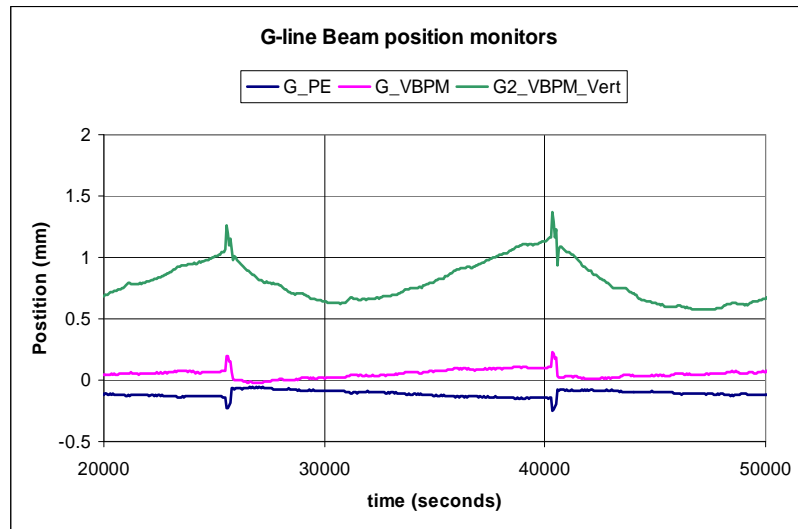
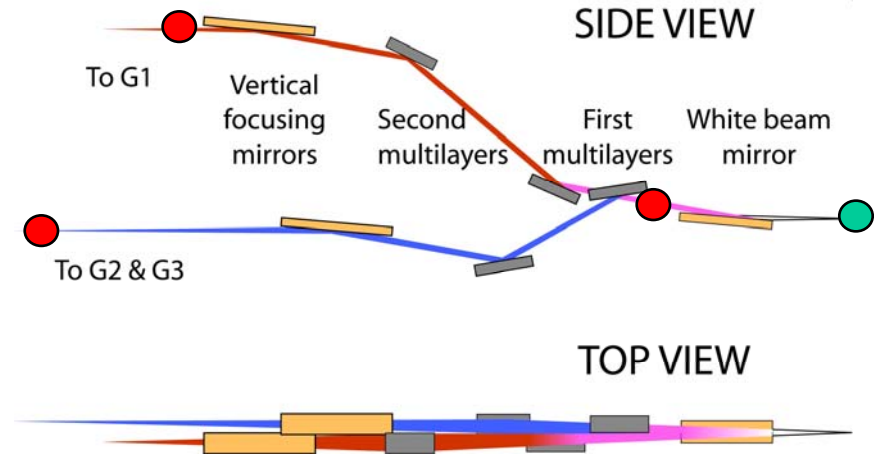
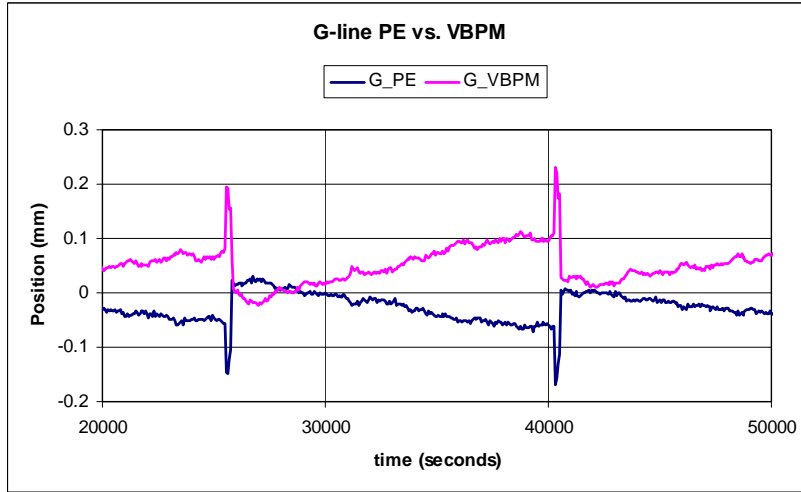


The Video BPM image of He-luminescence at G-cave. Here beam reflected from the mirror upstream is shown.



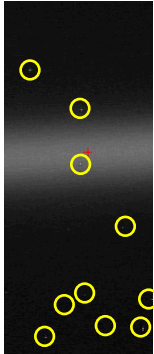


G-line position signals





Some VBPM pitfalls



- Offset effect on position
- Noise and ground-loops
- “Zingers”
- Intensity saturation
- Contamination, humidity

To minimize these effects:

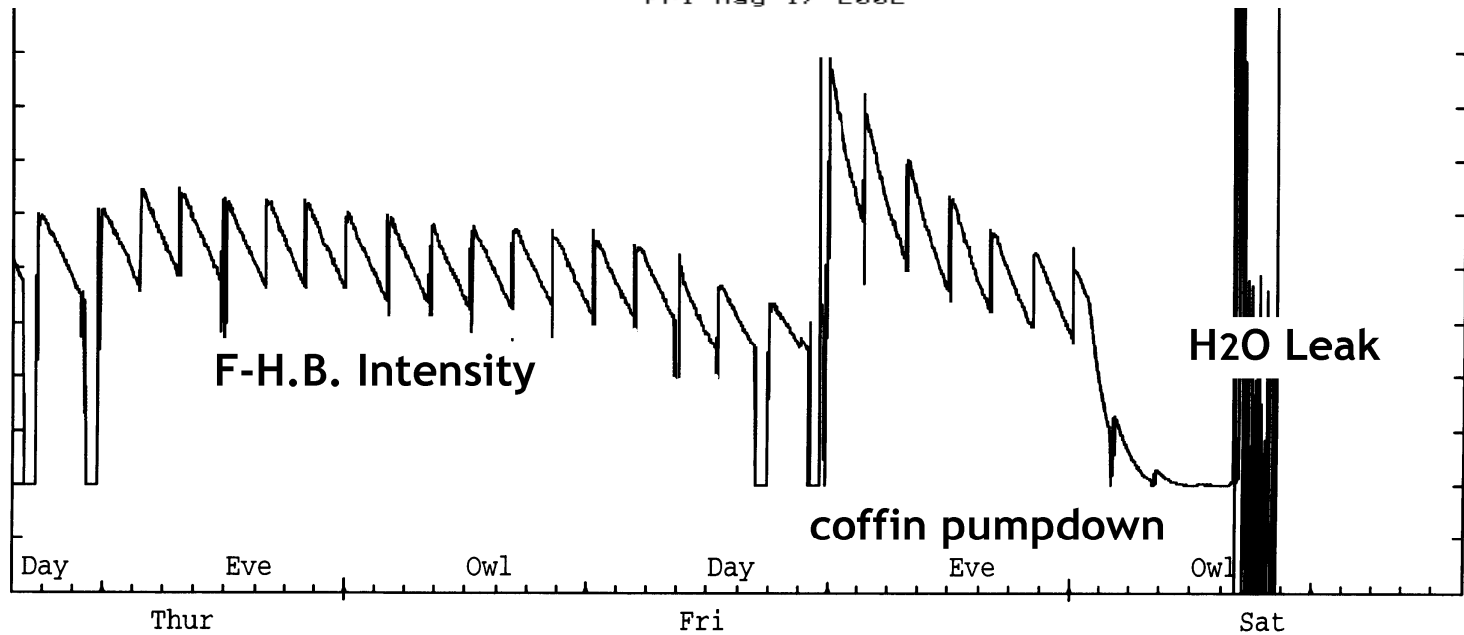
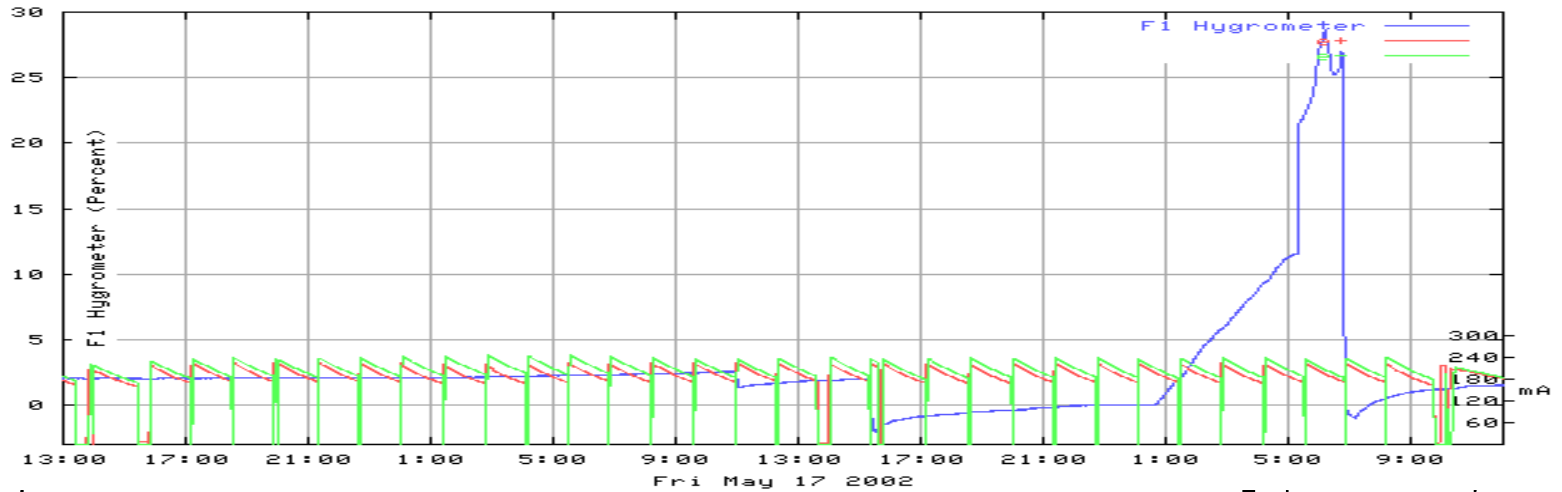
- Eliminate background light, adjust offset
- Short video cables, filters and video amplifiers, ultimately use digital camera
- Image filtering i.e. median, shilding
- Optimize optics, shutter time.





Humidity effects He luminescence !

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Conclusion and Summary

Video BPMs give multitude of important operational information about X-ray beam conditions.

The future:

Application of intelligent cameras, where the frame processing is inside the camera with built-in FPGA and DSP. This will reduce noise, the network data traffic volume and make possible faster frame capture.

references

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Nuclear Instruments & Methods in Physics Research, Section A **540**, n 2-3, 470-9 (2005)

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